LORD PRODUCT DATASHEET

Torque-Link[™]-LXRS[®]

Wireless Torque Sensor

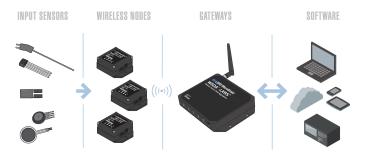


Torque-Link[™]-LXRS[®] - specialized analog sensor node designed to fit over rotating shafts for wireless strain and torque measurements

LORD Sensing LXRS® Wireless Sensor Networks enable simultaneous, high-speed sensing and data aggregation from scalable sensor networks. Our wireless sensing systems are ideal for test and measurement, remote monitoring, system performance analysis, and embedded applications.

The gateways are the heart of the LORD Sensing wireless sensing system. They coordinate and maintain wireless transmissions across a network of distributed wireless sensor nodes. Some nodes have integrated sensors, while others are designed with multi-sensor connectivity for application flexibility. The LORD Sensing LXRS wireless communication protocol between LXRS nodes and gateways enable high-speed sampling, ±32 microseconds node-to-node synchronization, and lossless data throughput under most operating conditions.

Users can easily program nodes for data logging, continuous, and periodic burst sampling with the Node Commander [®] software. The web-based SensorCloud[™] interface optimizes data aggregation, analysis, presentation, and alerts for gigabytes of sensor data from remote networks.



Product Highlights

- Two to four inch shaft (standard), more sizes available on request
- One or two differential analog input channels designed for full-bridge strain gauge integration
- Ideal for static and dynamic torque measurements with full temperature compensation and bending cancellation
- Rugged ABS housing designed for remote, long-term installation on cylindrical shafts
- User-programmable sample rates up to 4096 Hz
- · Application-specific design available on request

Features and Benefits

High Performance

• Lossless data throughput and node-to-node sampling synchronization of $\pm 32~\mu S$ in LXRS®-enabled modes

Ease of Use

- · Wireless framework reduces installation complexity
- Installs over existing strain elements and shafts with no mechanical modifications
- Configurable housing geometry will accommodate any shaft size.
- Easy custom integration with open-source, comprehensive communications and command library
- Wireless data transmission allows installation on rotating components without a slip ring

Applications

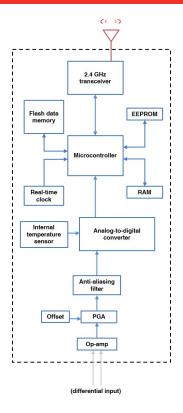
- · Condition-based monitoring
- Health monitoring of rotating components, aircraft, structures, and vehicles
- Static and dynamic torque measurements

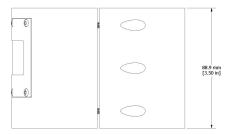


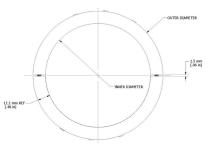
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Specifications

	General		
Sensor input channels	Differential analog, 1 channel (standard), 2 channels (optional)		
Integrated sensors	Internal temperature, 1 channel		
Data storage capacity	2 M Bytes (up to data points)		
Analog Input Channels			
Measurement range	Strain: full-bridge, ≥ 350 Ω		
Resolution	16 bit		
Accuracy	±0.1 % full scale typical		
Anti-aliasing filter bandwidth	Single-pole Butterworth		
-	-3 dB cutoff @ 500 Hz		
Bridge excitation voltage	+3 V dc (pulsed @ sample rates ≤ 16 Hz to conserve power)		
Measurement gain and offset	User-selectable in software, gain values from 20 to 2560		
Integrated Temperature Channel			
Measurement range	-40 °C to 85 °C, ±2 °C (at 25 °C) typical		
Resolution	12 bit		
Sampling			
Sampling modes	Synchronized, low duty cycle, datalogging		
	Continuous sampling: 1 sample/hour to 512 Hz		
Sampling rates	Periodic burst sampling: 32 Hz to 4096 Hz		
	Datalogging: 32 Hz to 4096 Hz		
Sample rate stability	±3 ppm		
Network capacity	Up to 2000 nodes per RF channel depending on sampling settings. Refer to the system bandwidth calculator:		
	http://www.microstrain.com/configure-your-system		
Synchronization between nodes	± 32 µsec		
Synomeon Between nodes	Operating Parameters		
Wireless communication range	100 m (typical)		
RF communication protocol	IEEE 802.15.4		
·	Replaceable, non-rechargeable battery pack (3.0 V dc, 1.2 Ah		
Power source	Li/MnO ² batteries in series configuration)		
Power consumption	1 to 25 mA (configuration dependent, see user manual)		
Operating temperature	-20 °C to +80 °C		
Angular acceleration limit	500 g standard (high g option available)		
Maximum RPM	2500 to 4200 RPM (diameter dependent, see user manual,		
	high RPM option available)		
	Physical Specifications		
Dimensions	Height 88.9 mm (3.5 inches), ID varies for use on 50.8 to 152.4 mm (2 to 6 inch) diameter shafts (custom sizes		
Dimensions	available)		
Weight	200 to 525 grams (0.44 to 1.16 lb), depending on size		
Facility and a state of the sta	IP 66, tested to DO-160 standards for temperature variation,		
Environmental rating	humidity, and vibration		
Enclosure material	ABS thermoplastic		
	Integration		
Compatible gateways	All WSDA base stations and gateways		
Compatible sensors	Differential analog sensors		
Connectors	Strain guage and battery interface connectors		
Shunt calibration	Internal shunt calibration resistor 499 KΩ		
Software	SensorCloud™, Node Commander®, Windows 7 (or newer)		
	Open-source MicroStrain Communications Library (MSCL) with sample code available in C++, Python, and .NET formats		
Software development kit (SDK)	(OS and computing platform independent)		
. , ,	http://www.microstrain.com/software/mscl		
	500 (U.O.) 10 (O) POLICE		
Regulatory compliance	FCC (U.S.), IC (Canada), ROHS		







example diameters (other sizes available

example diameters (editor elect divaliable)		
Shaft	Torque-Link	
Shaft Diameter	Inner Diameter	Outer Diameter
50.8mm [2.00 in]	51.3mm [2.02 in]	75.7mm [2.98 in]
76.2mm [3.00 in]	76.7mm [3.02 in]	101.1mm [3.98 in]
101.6mm [4.00 in]	102.1mm [4.02 in]	126.5mm [4.98 in]
127.0mm [5.00 in]	127.5mm [5.02 in]	151.9mm [5.98 in]
152 4mm [6 00 in]	152 9mm [6 02 in]	177 3mm [6 98 in]



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