

PRODUCT DATA SHEET

3DM-CV5-AR: **Vertical Reference** Unit

measurements, computed attitude, and navigation solutions.

The Inertial Measurement Unit (IMU) includes direct measurement of acceleration, angular rate, Delta-theta, and Delta-velocity. Compensation options include automatic compensation for magnetic anomalies, gyro and accelerometer noise, and noise effects. In models that include computed outputs, sensor measurements are processed through and auto-adaptive estimation filter algorithm to produce high accuracy computed outputs under dynamic conditions. The computed outputs vary between models and can include roll, pitch, and yaw. All sensors are fully temperature-compensated and calibrated over the operating temperature. Micro-Electro-Mechanical Systems (MEMS) technology allows for highly accurate, small, lightweight devices.

SensorConnect software is a user friendly program for device configuration. MIP Monitor (MicroStrain Inertial Protocol) can also be used. Both packages provide for device configuration, live data monitoring, and recording. Alternatively, the MIP Data Communications Protocol is available for development of custom interfaces and easy OEM integration.

The sensor operates independent of computer platform, operating system, or coding language.



The 3DM-CV5 family of industrial-grade, board-level inertial sensors provides a wide range of triaxial inertial

PRODUCT HIGHLIGHTS

- Triaxal accelerometer, gyroscope, and temperature sensors achieve the optimal combination of measurement qualities
- Dual on-board processors run a new Auto-Adaptive Extended Kalman Filter (EKF) for outstanding dynamic roll, pitch and yaw performance
- Smallest, lightest, highest performance VRU in its class

BEST IN CLASS PERFORMANCE

- Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- Bias tracking, error estimation, threshold flags, and adaptive noise modeling allow for fine tuning to conditions in each application
- High-performance, economical solution
- Direct PCB mount or chassis mount with ribbon cable
- Precision mounting alignment features

EASE OF USE

- SensorConnect enables simple device configuration, live data monitoring, and recording
- Optional hardware communications-development kit available
- The MSCL API allows easy integration with C++, Python, .NET. C#. Visual Basic. LabVIEW and MATLAB environments
- MIP open byte level communication protocol

COST EFFECTIVE

- Out-of-the-box solution reduces development time
- Volume pricing available

APPLICATIONS

- Unmanned vehicle navigation
- Robotics
- Platform stabilization, artificial horizon
- Health and usage monitoring of vehicles

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General		
Integrated Sensors	Triaxial accelerometer, triaxial gyroscope, pressure altimeter and temperature sensors	
Data Outputs	Inertial Measurement Unit (IMU) outputs: acceleration, angular rate, magnetic field, ambient pressure, Delta-theta, Delta-velocity COMPUTED OUTPUTS Extended Kalman Filter (EKF): filter status, timestamp, attitude estimates (in Euler angles, quaternion, orientation matrix), linear and compensated acceleration, bias compensated angular rate, pressure altitude, gravity-free linear acceleration, gyroscope and accelerometer bias, scale factors and uncertainties, gravity and magnetic models, and more. Complementary Filter (CF): attitude estimates (in Euler angles, quaternion, orientation matrix) stabilized, north and up vectors, GNSS	
Computed Outputs		
Attitude accuracy	EKF outputs: ±0.5° RMS roll and pitch (typ) CF outputs: ±0.8° RMS roll and pitch (typ)	
Attitude heading range	360° about all axes	
Attitude resolution	0.05°	
Attitude repeatability	0.5°	
Calculation update rate	500 Hz	
Computed data output rate	EKF outputs: 1 Hz to 500 Hz CF outputs: 1 Hz to 1000 Hz	

Inertial Measurement (IMU) Sensor Outputs		
	Accelerometer	Gyroscope
Measurement Range	±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g (optional)	±500°/sec (standard) ±250°, ±1000°/sec (optional)
Non-linearity	±0.04% fs	±0.06% fs
Resolution	0.05 mg (+/- 8 g)	<0.003°/sec (500 dps)
Bias instability	±0.08 mg	8°/hr
Initial bias error	±0.004 g	±0.01°/sec
Scale factor stability	±0.05%	±0.05%
Noise density	100 µg/√Hz (2 g)	0.0075°/sec/√Hz (500°/sec)
Alignment error	±0.05°	±0.08°
Bandwidth	225 Hz (max)	500 Hz (max)
Offset error over temperature	0.02% (typ)	0.01% (typ)
Gain error over temperature	0.05% (typ) ±0.2% (max)	0.1% (typ) ±0.4% (max)
Sampling rate	1 kHz	1 kHz
IMU Filtering	First stage sigma delta Analog to Digital Converter sampled at 1 kHz. Second stage user adjustable digital low pass filter.	
IMU data output rate	1 Hz to 1 kHz (sensor direct mode)	
	Pressure Altimete	r
Altitude Range	-1800 m to 10,000 m	
Resolution	< 0.1 m	
Relative Accuracy	0.01 hPa RMS	
Sampling rate	25 Hz	

Operating Parameters		
Communication	USB 2.0 (full speed), TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default 115,200)	
Power source	+3.2 to +5.2 V dc	
Power consumption	360 mW (typ), 500 mW (max)	
Operating tempe- rature	-40°C to + 85°C	
Mechanical shock limit	500g/1ms absolute maximum survivability.*	
MTBF	1,035,471 hours (Telcordia method gm/35C)	
Physical Specifications		
Dimensions	38 mm x 24 mm x 9.7 mm	
Weight	11 grams	
Enclosure material	Aluminum	
Regulatory compli- ance	CE, REACH, RoHS	
Intregration		
Connectors	Data/power output: Micro-D9 Samtec FTSH Series	
Software	SensorConnect and MIP Monitor software included; Windows XP/Vista/7/8/10 compatible	
Data Communicati- ons Protocol (DCP)	Protocol compatibility across GX3, GX4, RQ1, GQ4, GX5, CX5 and CV5 product families	
Software develop- ment kit (SDK)	MicroStrain Communication Library (MSCL) open source license includes full documentation and sample code.	
Hardware development kit	Option purchased separately	

*Prolonged exposure to >2x full scale range can result in permanent damage. See manual for details



