

#### PRODUCT DATA SHEET

# 3DM-CX5-AR: Vertical Reference Unit

The MicroStrain 3DM-CX5 family of high performance, industrial-grade, board-level inertial sensors provides a wide range of triaxial inertial measurements, computed attitude, and navigation solutions.

In all models, the Inertial Measurement Unit (IMU) includes direct measurement of acceleration and angular rate, and is fully temperature-compensated and calibrated over the operating temperature. The use of Micro-Electro-Mechanical System (MEMS) technology allows for highly accurate, small, lightweight devices.

SensorConnect software is a user friendly program for device configuration. MIP Monitor (MicroStrain Inertial Protocol) can also be used. Both packages provide for device configuration, live data monitoring, and recording. Alternatively, the MIP Data Communications Protocol is available for development of custom interfaces and easy OEM integration.

The sensor operates independent of computer platform, operating system, or coding language.

# **PRODUCT HIGHLIGHTS**

- Triaxal accelerometer, gyroscope, and temperature sensors achieve the optimal combination of measurement qualities
- Dual on-board processors run a new Auto-Adaptive Extended Kalman Filter (EKF) for outstanding dynamic attitude estimates
- Smallest, lightest, highest performance VRU in its class



#### **BEST IN CLASS PERFORMANCE**

- Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- Bias tracking, error estimation, threshold flags, and adaptive noise modeling allow for fine tuning to conditions in each application
- High-performance, low-drift gyros with low noise density and vibrational rectification error
- Accelerometer noise as low as 20 ug/√Hz

### **EASE OF USE**

- SensorConnect enables simple device configuration, live data monitoring, and recording
- Optional hardware communications-development kit available
- The MSCL API allows easy integration with C++, Python, .NET, C#, Visual Basic, LabVIEW and MATLAB environments
- MIP open byte level communication protocol

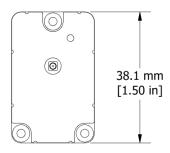
# **COST EFFECTIVE**

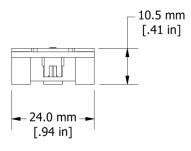
- Out-of-the-box solution reduces development time
- Volume pricing avaiable

# **APPLICATIONS**

- Unmanned vehicles
- Robotics
- · Platform stabilization, artificial horizon
- Health and usage monitoring of vehicles

General		
Integrated Sensors	Triaxial accelerometer, triaxial gyroscope, and temperature sensors	
Data Outputs	Inertial Measurement Unit (IMU) outputs: acceleration, angular rate, Delta-theta, Delta-velocity	
Computed Outputs		
Attitude accuracy	EKF outputs: ±0.25° RMS roll and pitch, (typ)  CF outputs: ±0.5° roll and pitch (static, typ)  and ±2.0° roll and pitch (dynamic, typ)	
Attitude heading range	360° about all axes	
Attitude resolution	< 0.01°	
Attitude repeatability	0.02° (typ)	
Calculation update rate	500 Hz	
Computed data output rate	EKF outputs: 1 Hz to 500 Hz  CF outputs: 1 Hz to 1000 Hz	





Inertial Measurement (IMU) Sensor Outputs			
	Accelerometer	Gyroscope	
Measurement Range	±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g (optional)	300°/sec (standard) ±75, ±150, ±900/sec (optional)	
Non-linearity	±0.02% fs	±0.02% fs	
Bias instability	±0.04 mg	8°/hr	
Initial bias error	±0.002 g	±0.04°/sec	
Scale factor stability	±0.03%	±0.05%	
Noise density	20 μg/√Hz (2 g)	0.005°/sec/√Hz (300°/ sec)	
Alignment error	±0.05°	±0.05°	
Bandwidth	225 Hz (max)	250 Hz (max)	
Offset error over temperature	0.06% (typ)	0.04% (typ)	
Gain error over temperature	0.03% (typ)	0.03% (typ)	
Scale factor non- linearity (@ 25°C)	0.02% (typ) 0.06% (max)	0.02% (typ) 0.06% (max)	
Vibration induced noise		0.072°/s RMS/g RMS	
Vibration recti- fication error (VE)	0.03%	0.001°/s/g² RMS	
Sampling rate	1 kHz	4 kHz	
IMU Filtering	Digital sigma-delta wide band anti-aliasing filter to digital averaging filter (user adjustable) scaled into physical units.		
IMU data output rate	1 Hz to 1000 Hz		
	Pressure Altimeter		
Altitude Range	-1800 m to 10,000 m		
Resolution	< 0.1 m		
Relative Accuracy	0.01 hPa RMS		
Sampling rate	25 Hz		

Operating Parameters		
Communication	USB 2.0 (full speed), TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default 115,200)	
Power source	+3.2 to +5.2 V dc	
Power consumption	500 mW (typ)	
Operating temperature	-40°C to +85°C	
Mechanical shock limit	500g/1ms absolute maximum survivability.*	
MTBF	400,094 hours (Telcordia method, GM/35C)	
Physical Specifications		
Dimensions	38 mm x 24 mm x 9.7 mm	
Weight	8 grams	
Enclosure material	Aluminum	
Regulatory compli-	CE, REACH, RoHS	
Intregration		
Connectors	Data/power: Samtec FTSH Series	
	Connectivity kit: Micro-D9	
Software	SensorConnect and MIP Monitor software included; Windows XP/Vista/7/8/10 compatible	
Data Communications Protocol (DCP)	Protocol compatibility across GX3, GX4, RQ1, GQ4, GX5, CX5 and CV5 product families	
Software develop- ment kit (SDK)	MicroStrain Communication Library (MSCL) open source license includes full documentation and sample code.	
Hardware development kit	Option purchased separately	

<sup>\*</sup>Prolonged exposure to >2x full scale range can result in permanent damage. See manual for details

MicroStrain by HBK 459 Hurricane Lane Williston, VT 05495 - USA